# Product Manual

# **Case Deflector (Accessory)**

Application Guidelines, Specifications, Installation Procedures, Maintenance, and Spare Parts



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Read these documents thoroughly before attempting to perform maintenance or repairs to the applicable Intelligrated conveyor system components or devices. Exercise extreme caution when working around moving and rotating conveyor equipment. Wear the proper clothing and safety equipment. DO NOT attempt to perform any maintenance until the equipment is de-energized, locked out and tagged out in accordance with established company procedures.

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#### SECTION A:PRODUCT SUMMARY

**CSPS Designations: Arm Face** Left Hand **Right Hand** 

> Plain Face CLP **CRP UHMW Face** CLU **CRU** Wheel Face **CLW CRW**

**Description:** Deflector arm pivots to divert product onto gravity or powered take-away junction.

Case deflector can be installed on any CS powered belt or roller mainline conveyor.

**Arm Faces** ■ Plain-face 2 sides

Available: ■ UHMW-face 1 side & plain face 1 side

■ Uhmw-face 2 sides

■ Wheel-face 1 side & plain face 1 side

■ Wheel-face 2 sides

**Installation Options:** Junction side or opposite side;

Right-hand or left-hand.

**Mainline Conveyor** 

 Accuglide Plus Live Roller Conveyor Line Shaft Live-Roller Conveyor **Models Supported:**  A/CQ Chain-Powered Roller ■ T/C Chain-Powered Roller Conveyor

Conveyor ■ V-Belt Live Roller Conveyor

■ E-Z Set Live Roller Conveyor

**Mainline Conveyor** 16", 22", 28", 34" & 40"

Widths Supported: **Minimum Product** 

Height:

Plain Face 1 5/8" **UHMW Face** 1 7/8"

Wheel Face 1 1/4"

**Maximum Product** 

Weight:

100 lbs.

Actuator: Dual-action air cylinder – 4" bore x 8" stroke, with air cushions at both ends; 60 to 80

PSI.

Control: 4-way solenoid valve

**Mainline Conveyor** 

Speed:

Up to 250 FPM

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## SECTION B:APPLICATION GUIDELINES

## Introduction

The CS Case Deflector is designed to divert products from a mainline conveyor to a takeaway junction. Mounted to a mainline conveyor, the case deflector incorporates an arm which pivots on a vertical axis between the "deflect" and "bypass" positions. Product approaching the case deflector on the mainline conveyor will be routed according to the position of the deflector arm, as follows:

- When the deflector arm is in the "deflect" position, product is diverted to the take-away junction.
- When the deflector arm is in the "bypass" position, product continues to move along the mainline conveyor, bypassing the junction.

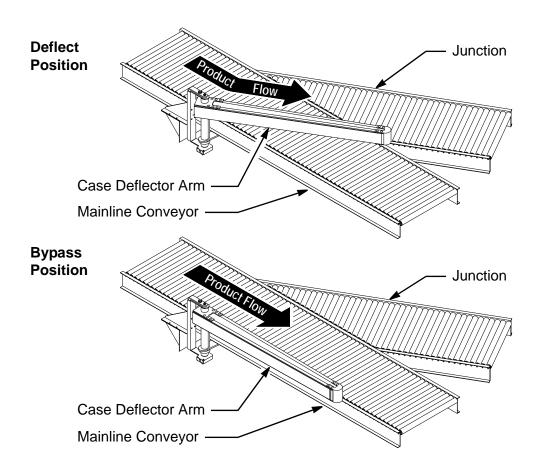


Figure B - 1 — Case Deflector Arm Positions



## **Features**

#### **Pneumatic Actuator**

Movement of the deflector arm is powered by a pneumatic actuator mounted to the support frame, which is mounted to the underside of the mainline conveyor (see Figure B - 2). A clevis attached to the cylinder shaft is connected to the free end of the pivot arm, which is mounted to the pivot assembly underneath the mainline conveyor.

The pneumatic cylinder is controlled by a three-way solenoid valve, which provides positive air pressure for both "deflect" and "bypass" movements. Optional proximity switches are available for confirming that the arm is in the "deflect" or "bypass" position.

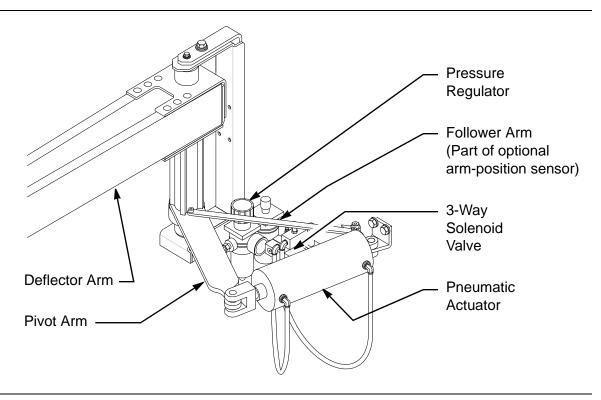


Figure B - 2 - Pneumatic Components

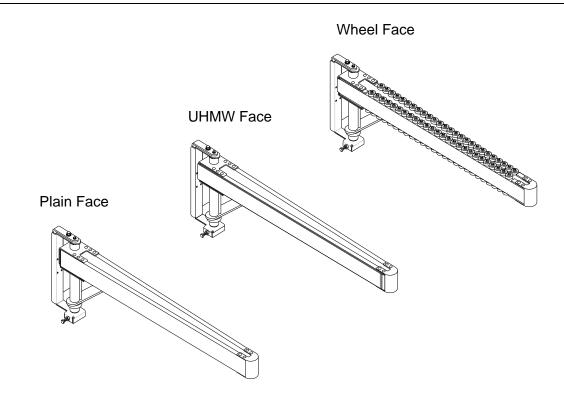
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# **Available Arm Faces**

The case deflector is available with any of three arm faces (see Figure B - 3):

- Plain face;
- UHMW face (1-sided or 2-sided); and
- Wheel face (1-sided or 2-sided).



#### Note:

UHMW Face & Wheel Face deflector arms are available as follows:

UHMW Face: 1 Side UHMW Face & 1 Side Plain Face

2 Sides UHMW Face

Wheel Face: 1 Side Wheel Face & 1 Side Plain Face

2 Sides Wheel Face

Figure B - 3 - Available Arm Faces



# **Arm Position Sensors (Optional)**

The case deflector is available with optional arm-position sensors (see Figure B - 4). Arm-position sensors detect when the deflector arm is either in the "deflect" position or in the "bypass" position. The arm-position sensor assembly is mounted to the case deflector frame underneath the mainline conveyor, adjacent to the pneumatic actuator.

The arm-position sensor assembly consists of a pivoting target linked to the operating arm, and a pair of proximity switches. When the pivoting target moves to either terminal position, the corresponding proximity switch is triggered. The resulting signal may be routed or processed as necessary.

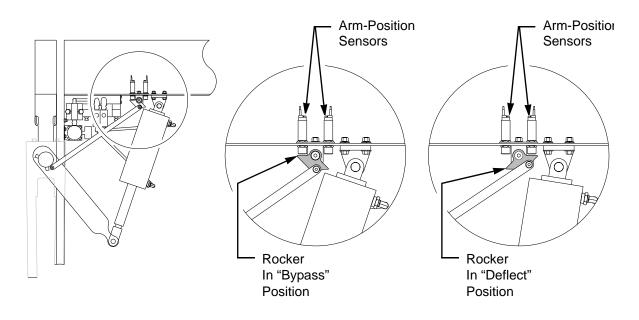


Figure B - 4 - Arm-Position Sensors (Optional)

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# **Case Deflector Mounting Arrangements**

The case deflector is available for any of four mounting arrangements, according to the following variables (see Figure B - 5):

- Left-hand or right-hand; and
- Junction side or opposite side.

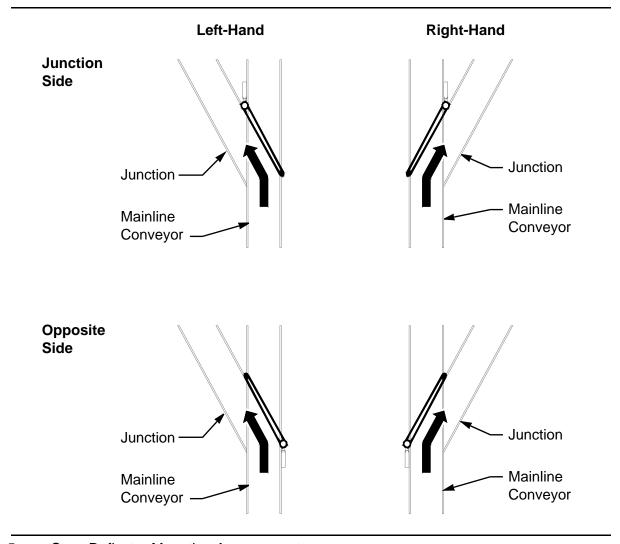


Figure B - 5 - Case Deflector Mounting Arrangements



# **Recommended Applications**

The case deflector is recommended for applications requiring the selective routing of "trains" of products. It should not be used for sortation of individual products. The solenoid valve may be wired either for automated control or for manual control, such as with a remote manual switch.

A typical application might be a system in which merge sections supply product to two manual loading stations (see Figure B - 6). One loading station may be adequate to support normal periods, but peak periods may require that a second station be used. In this case, a secondary loading station can be located between two merge sections, with a case deflector located at the junction leading to the secondary station. During normal periods, the case deflector remains in the "bypass" position, allowing product to proceed to the primary loading station. During peak periods, the case deflector is switched to the "deflect" position, rerouting product to the secondary loading station. In this instance, engagement of the case deflector may be controlled by a manually operated remote switch located at the primary loading station.

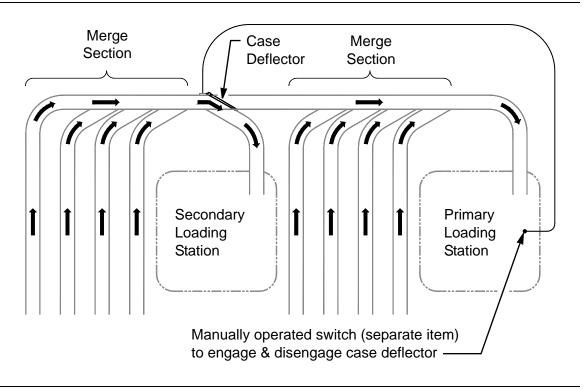


Figure B - 6 — Manual Loading Station Application

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Another typical application might be a system in which multiple lanes of accumulation conveyor are to be filled sequentially. When one lane is full, the next lane is filled, and so on (see Figure B - 7). In this situation, continuous trains of product are diverted to a single lane at a time. Such an application lends itselfwell to automated control.

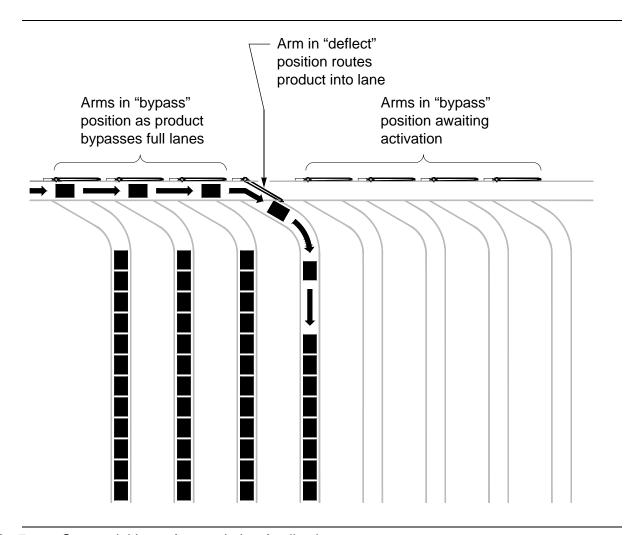


Figure B - 7 - Sequential Lane Accumulation Application



# **Application Considerations**

### **Conveyor Requirements**

#### Mainline Conveyor

Powered-roller mainline conveyors are recommended for case-deflector applications, including the following models:

- Accuglide Plus Live Roller Conveyor (6 3/8" deep side rail);
- A/CQ Chain-Powered Roller Conveyor(5 1/2" deep side rail);
- E-Z Set Live Roller Conveyor (6 3/8" deep side rail);
- Line Shaft Live-Roller Conveyor (5 1/2" deep side rail);
- T/C Chain-Powered Roller Conveyor (5" deep side rail); and
- V-Belt Live Roller Conveyor (10" deep side rail).

If powered-belt conveyor is used as a mainline conveyor, consideration should be made for the deflection of cartons across the carrying surface. Since the deflector arm must be held stationary in the "deflect" position while product is being deflected, the deflecting force is derived solely from the mainline conveyor. Friction between the product and the surface of the deflector arm must also be taken into consideration.

The width of the mainline conveyor is a factor in determining product spacing, since deflector arm is a function of mainline-conveyor width.

#### Take-Away Conveyor

The types of conveyor suitable for take-away application include the following:

- Powered roller conveyor;
- Gravity-roller conveyor; or
- · Gravity-wheel conveyor.

If gravity roller or gravity wheel conveyor is used for take-away application, the take-away junction should be pitched downward away from the mainline conveyor.

A powered take-away conveyor should operate at a vector speed at least 1.155 times the speed of the mainline conveyor. For example, if the mainline conveyor is operating at 250 FPM, then the take-away conveyor should operate at 290 FPM or greater.

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#### **Product Considerations**

#### General

If a case deflector is to be specified for an application, the following aspects of product should be considered:

- Maximum product weight: 100 pounds.
- Product should be capable of sliding across the carrying surface of the mainline conveyor.
- The product should be capable of withstanding the force of impact with the arm without carton damage. At the area of contact with the deflector arm, the carton should be firm enough that damage to the carton will not occur.
- Product should be stable. The center of gravity should be low enough in relation to the product height to avoid tipping over when a package encounters the deflector arm.
- The width of the product in relation to its length should not require the product to extend outside the permissible product-travel envelope as it is being deflected.

Product characteristics also affect the selection of arm face, as follows:

- Packaging materials should not have a coefficient of friction so high that it interferes
  with effective deflection. Products make contact both with the carrying surface and with
  the surface of the deflector arm itself. If friction is a concern, the UHMW-face or the
  wheel-face deflector arm is recommended.
- For light-weight cartons having plain cardboard exterior surfaces, the plain-face arm is satisfactory.
- For medium-weight cartons and for cartons having a surface coefficient of friction, such as shrink-wrapped cartons, the UHMW-face arm is recommended; and
- For heavy-weight cartons, the wheel-face arm is recommended.

## Product Height

The case deflector is suitable for a range of carton heights, depending on the arm face and on the arm height adjustment (see Figure B - 8). Recommended minimum carton height is based on 1/2" minimum engagement between the carton and the bearing surface of the arm. Maximum height depends on the center of gravity of the carton in relation to the top of the bearing surface of the arm.

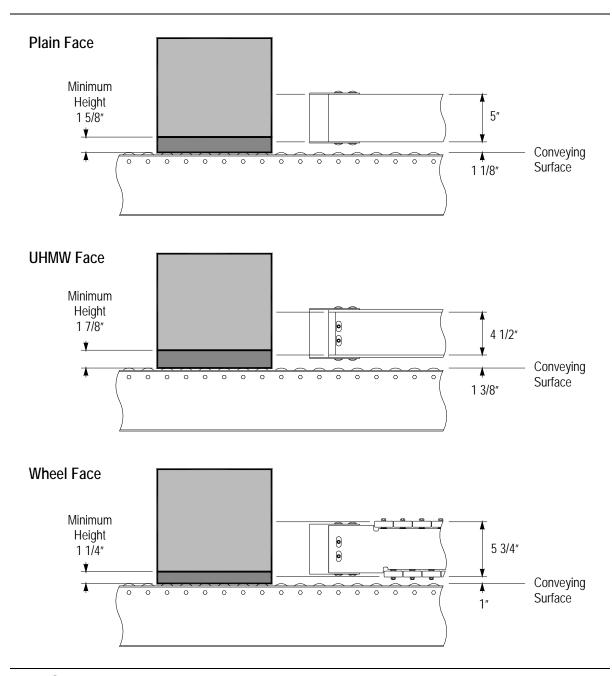


Figure B - 8 - Carton Height

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# **Operating Speed**

The operating speed of the case deflector is a function of the air-pressure regulator and of the flow-control valves. Under ordinary operating conditions, a single arm movement in one direction (either from the "bypass" position to the "deflect" position, or vice versa) should be expected to take between two and four seconds.

Note that the faster the operating speed, the more abruptly the deflector arm stops in either terminal position. Very fast arm action will cause significant vibration of the deflector arm, and consequently of the conveyor. If fast operation is required, floor supports or ceiling hangers should therefore be located as close as possible to the case deflector, and the distance between supports or hangers should be as small as possible on either side of the case deflector.

#### **Product Spacing**

Product spacing includes the gap between trains of product and the gap within a train of product (see Figure B - 9).

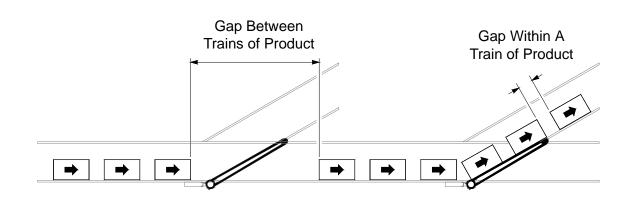


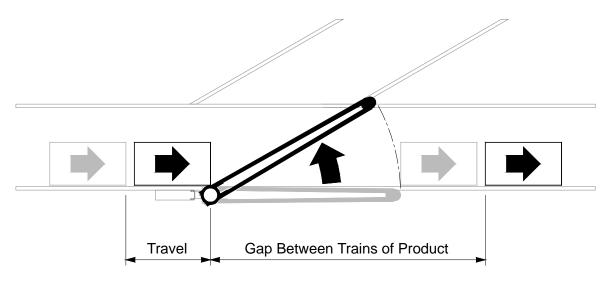
Figure B - 9 — Gap Between Trains and Gap Within a Train

## Gap Between Trains of Product

The gaps at both ends of a train of diverted product (both the leading gap and the trailing gap) should be large enough to accommodate operation of the deflector arm. The values shown for the gap between trains are based on an arm-action time of 3 seconds in either direction ("deflect" or "bypass"). For other operating speeds, adjust the gap accordingly.

Mainline Conveyor Speed (FPM)	N	lainline Co	nveyor Wi	dth (Inche	s)
	16	22	28	34	40
150	138	146	158	170	182
200	168	176	188	200	212
250	198	206	218	230	242

Table B.1 - Gap Between Trains of Product (Inches)



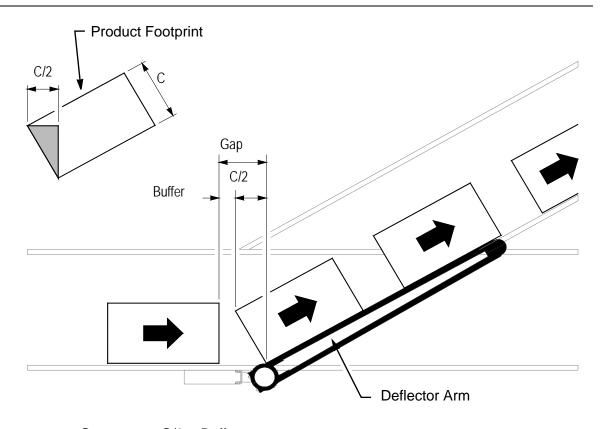
**Note:** Travel shown indicates product travel during arm action.

Figure B - 10 — Gap Between Trains of Product ("Deflect" Arm Action Shown)

Gap Within Trains

The gaps within a train of diverted product should consist of a corner factor large enough to accommodate the rotation of product, plus a buffer allowance as necessary for safe clearance. The corner factor is normally equal to one-half the product width. A buffer allowance of approximately 4 to 6 inches is suggested. If product or carrying surface allows significant product slippage, adjust the buffer allowance accordingly.

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Gap = C/2 + Buffer

C = Maximum Case Width

Buffer = Distance required for safe clearance.

Suggested buffer allowance = 4" - 6"

Figure B - 11 — Gap within Trains of Deflected Product



#### Corner Clearance

As a carton moves from the mainline conveyor to the take-away conveyor, the side of the carton oriented toward the inside of the turn may reach or even overhang beyond the corner where the side rails of the junction and the mainline conveyors meet. A judgment must be made concerning the degree to which overhang is acceptable. The factors determining whether overhang occurs include the following:

- · Conveyor width; and
- Maximum carton size.

To determine the occurrence or severity of overhang, making a plan-view layout drawing is recommended (see Figure B - 12). The layout drawing should show the worst-case scenario, using the combination of the largest carton length and the largest carton width. Several carton positions should be shown in sequence as the carton moves through the turn. Note that the leading corner on the outside of the turn remains in contact with the deflector arm as the carton moves into and through the turn.

Make a layout showing the largest carton size positioned sequentially through the turn onto the junction. Make certain that the carton does not extend beyond the allowable limits.

Largest Carton

Mainline

Conveyor

Figure B - 12 - Corner Clearance

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#### Product Orientation

To maintain consistent product orientation through the turns, make certain that products are placed on the mainline conveyor with their longer sides oriented parallel to the direction of travel (see Figure B - 13). Products with a square footprint may tend to rotate out of proper orientation.

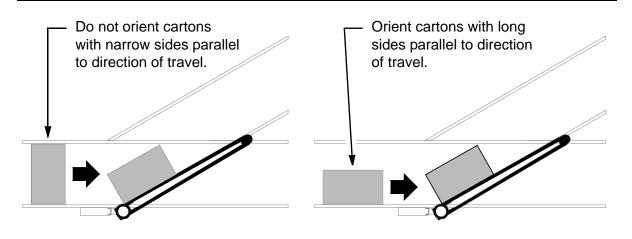


Figure B - 13 — Maintaining Carton Orientation



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#### SECTION C:SPECIFICATIONS

#### **CS Case Deflector**

#### **Standard Features**

Support Frame

7 gage formed steel.

#### Pivot Assembly

14" steel channel frame - 2 1/2" O. D. x 11 gage pivot roller, 1/2" thick steel pivot arm, 11/16" pivot axle, 2 bearings.

Arm

Five inch deep x 12 gage steel formed channels & 12 gage steel bull-nose weldment.

#### Control Components

**Pneumatic Cylinder** – Double-acting, 4" bore x 8" stroke with air cushions at both ends; 60 to 80 psi operating pressure.

**Solenoid Valve** – 3-position (open center); 4-way valve with manifold base (3/8" NPT ports); double-solenoid actuated; 120VAC/60Hz (standard) or Mac 24VDC (optional).

#### Filter-Regulator-Lubricator-Gage –

Filter-regulator with gage (maximum pressure: 150 psi) — Die-cast aluminum body with glass-filled bonnet, Buna N elastomer seals, ploycarbonate bowl with bowl guard, 40-micron filter element, manual drain, relieving regulator, zero-creep, machined brass valve seat, 3-position, nonrising adjustment knob and tamper-proof cap.

Lubricator – Aluminum housing, polycarbonate bowl with bowl guard, 3-position nonrising adjustment knob.

Flow Control Valves

# Capacity

Maximum carton weight: 100 lbs.

#### Mainline Conveyor Heights

Side rail heights: 5", 5 1/2", 6 3/8" & 10"

#### **Finish**

Powder coat, medium gray.

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# **Optional Features**

## Arm Face

Plain Face – 12 gage arm channel.

UHMW Face – 1/4" thick ultrahigh molectular weight (UHMW) polyethylene plate fastened to 12 gage steel arm channel

Wheel Face – No. 100 Steel (35 lb. capacity) 1 15/16" Dia. x 11/16" W, zinc-plated wheels mounted to top and bottom flanges of 12 gage arm channel on 2" centers.

# Arm-position Sensors (Optional)

Two 18mm proximity switches to detect "deflect" and "bypass" arm positions for control purposes; 120VAC or 24VDC.

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# SECTION D:ENGINEERING DATA

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# SECTION E: LAYOUT DIMENSIONS

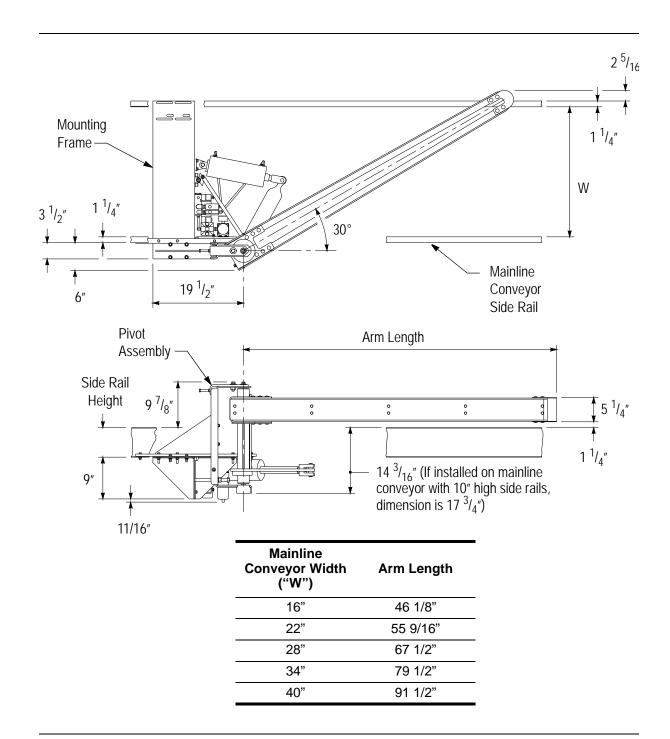
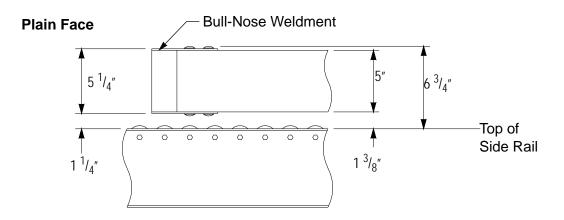
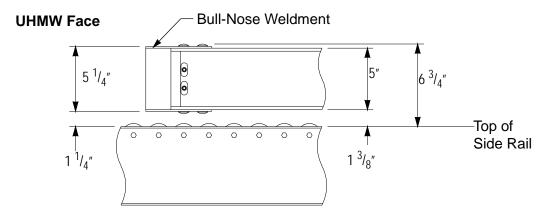
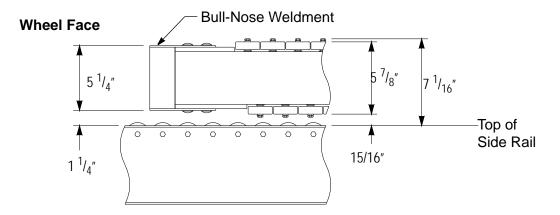


Figure E - 1 - General Dimensions

5330 12/03 E - 1



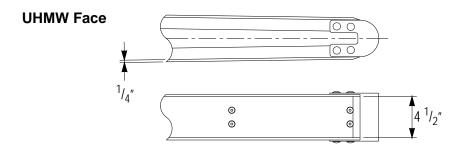




Note: Vertical clearance may vary depending on adjustment of deflector arm.

Figure E - 2 — Deflector Arm Vertical Dimensions

E-2 5330 12/03



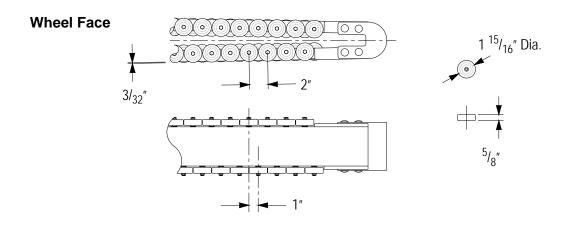


Figure E - 3 — Supplemental Arm Face Details

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## SECTION F: ACCESSORIES

# Introduction

# **Arm-Position Sensors (Optional)**

A pair of proximity switches for detecting deflector-arm position is available (see Figure F - 1). Linked to the deflector-arm pivot arm, a "rocker" is mounted to the support frame. The rocker pivots as the deflector arm pivots. The rocker has two target surface, which are detected by the proximity switches.

- When the deflector arm is in the "bypass" position, the "bypass" proximity switch is triggered
- When the deflector arm is in the "deflect" position, the "deflect" proximity switch is triggered.
- Proximity switches are available for both 110VAC and 24VDC.

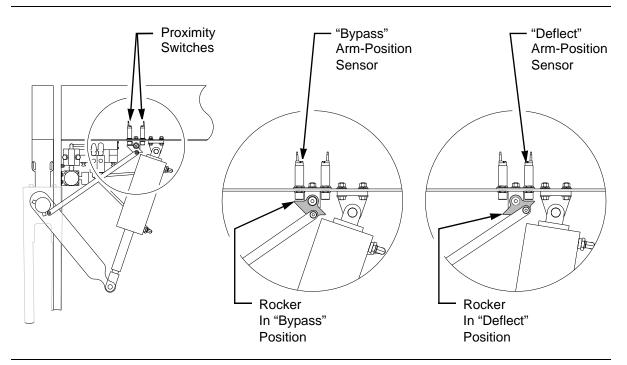


Figure F - 1 — Proximity Switches (Optional)

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#### SECTION G:INSTALLATION PROCEDURES

#### Introduction

# **Accepting Shipment**

Immediately upon delivery, check that all equipment received agrees with the bill of lading or carrier's freight bill. Any shipping discrepancy or equipment damage should be clearly noted on the freight bill before signing.

## Shortages or Errors

Report any shortages or errors to the Customer Service in writing within ten (10) days after receipt of shipment.

#### Note:

It is very important that you compare the Order Acknowledgment against the actual material received when you receive the shipment so you have enough lead time to order any missing parts. If you find that a part is missing during assembly, you may have to discontinue assembly while you wait for the part to arrive.

#### Lost or Damaged Shipment

Report lost shipments to our Shipping Department.

If shipping damage is evident upon receipt of the conveyor, note the extent of the damage on the freight bill and immediately contact the transportation carrier to request an inspection. Do not destroy the equipment crating and packing materials until the carrier's agent has examined them. Unless otherwise agreed by the seller, the Purchaser (user) shall be responsible for filing claims with the transportation carrier. A copy of the inspection report along with a copy of the freight bill should be sent to our Traffic Department.

#### Claims and Returns

All equipment furnished in accordance with the Manufacturer's Agreement is not returnable for any reason except when authorized in writing by the Seller. Notification of return must be made to the Customer Service Department, and if approved, a "Return Authorization Tag" will be sent to the Purchaser (user). The return tag, sealed in the "Return Authorization Envelope" should be securely affixed to the exterior surface on any side of the shipping carton (not Top or Bottom), or affixed to any smooth flat surface on the equipment, if not boxed.

Send authorized return shipment(s) transportation charges prepaid to the address indicated on the Return Authorization Tag. If initial shipment is refused, the Purchaser (User) shall be liable for all freight charges, extra cost of handling, and other incidental expenses.

#### Codes and Standards

The conveyor equipment is designed and manufactured to comply with the American National Standard Institute's "SAFETY STANDARDS FOR CONVEYORS AND RELATED EQUIPMENT" (ANSI/ASME B20.1) and with the National Electrical Code (ANSI/NFPA70).

The Purchaser/User shall be familiar with, and responsible for, compliance with all codes and regulations having jurisdiction regarding the installation, use, and maintenance of this equipment.

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## Warning Signs

Warning signs and labels posted on or near the conveyor equipment shall not be removed, painted over, or altered at any time. All safety devices, warning lights, and alarms associated with the conveyor system should be regularly tested for proper operation and serviced as needed. If the original safety item(s) become defective or damaged, refer to the conveyor parts list or bills-of-materials for replacement part numbers.

#### Safety Features

- Do turn off conveyor power source(s) and affix appropriate lockout/tagout device(s) to operating controls before servicing the equipment. ONLY trained and qualified personnel who are aware of the safety hazards should perform equipment adjustments or required maintenance while the conveyor is in operation.
- Do observe all warning signs, lights, and alarms associated with the conveyor operation and maintenance, and be alert at all times to automatic operation(s) of adjacent equipment
- Do use extreme caution near moving conveyor parts to avoid the hazard of hands, hair, and clothing being caught.
- Do not sit on, stand on, walk, ride, or cross (over or under) the conveyor at any time except where suitable catwalks, gates, or bridges are provided for personnel travel.
- Do not attempt to repair any equipment while the conveyor is running, replace any conveyor component without appropriate replacement parts, or modify the conveyor system without prior approval by the manufacturer.
- Do not operate the conveyor until all safety guards are securely in place, all tools and non-product materials are removed from or near the conveying surfaces, and all personnel are in safe positions.
- Do not remove or modify any safety devices provided on or with the conveyor.
- Do not clear jams or reach into any unit before first turning off the equipment power source(s) and affixing appropriate lockout/tagout device(s).

## **Parts Replacement**

To minimize production downtime, selected conveyor spare parts should be stocked for replacement of defective components when required. If quantity requirements or code numbers are not indicated on the conveyor parts list, refer to the equipment bill(s)-of-materials. For added convenience, a list of selected spare parts is included in this manual (see Section I).

# **Factory Assistance**

Contact Field Service for installation, operation, or maintenance assistance, or Customer Service and Support for replacement parts.

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# Installing the Case Deflector

# Preparation

Before installing the Case Deflector, prepare the unit as follows:

- To prevent damage to the air filter assembly, remove the bottom cover from the air filter (see Figure G - 1).
- Disconnect the cylinder-rod clevis from the pivot arm (see Figure G 2). Remove the retaining ring, and remove the clevis pin. To avoid damaging the retaining-ring flanges, use a punch to remove the clevis pin.
- To make the case deflector easier to handle during installation, remove the deflector arm from the pivot assembly. It is not necessary to disassemble the bull-nose weldment from the arm faces (see Figure G 3). Remove 12 carriage bolts, and slide the deflector arm away from the mounting frame.
  - Note that there are flat spacers between the flanges of wheel-face arms and the mounting frame.
- Remove the stiffener plate from the support frame (see Figure G 1).

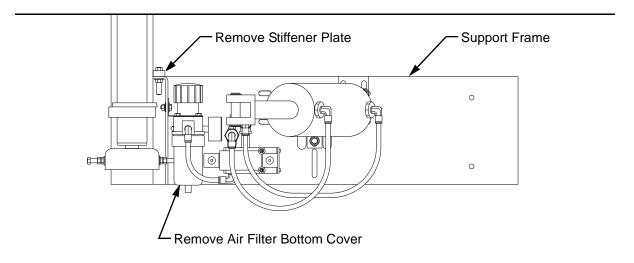


Figure G - 1 — Removing the Air Filter Bottom Cover and Stiffener Plate

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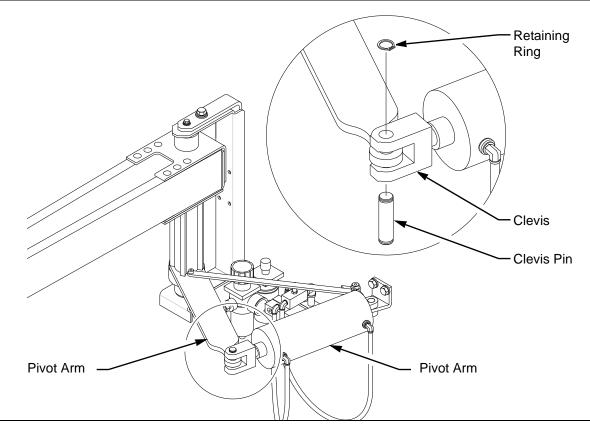


Figure G - 2 — Disconnecting the Pivot Arm

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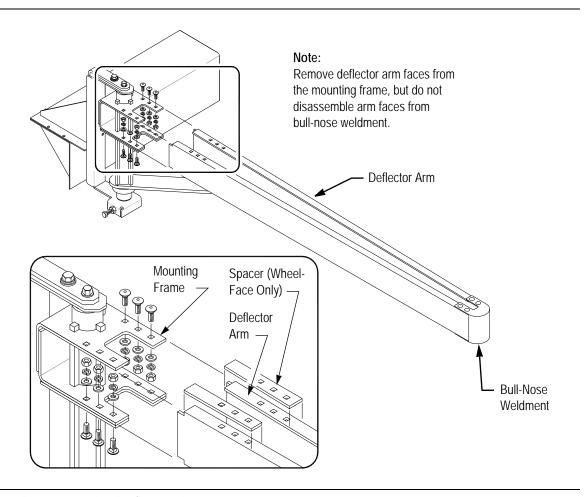


Figure G - 3 — Removing the Deflector Arm

#### **Determine the Installation Location**

The correct mounting position for the Case Deflector is a matter of judgment, depending on the precise product-path requirements, the side-guide arrangement, etc. Typically, the Case Deflector should be mounted so that the diverted product path clears the side guides (see Figure G - 4 and Figure G - 5).

The mounting position may be adjusted to accommodate critical features at the junction. For example, if the mounting position of the side guides allows for product to hang over the junction side rail, the case-deflector mounting position may be shifted in the product-flow direction of the mainline conveyor. On the other hand, if the side guides are set in from being flush with the side rails, then the Case Deflector mounting position should be shifted in the opposite direction. Since the deflector arm must be removed for mounting the unit, the mounting location should be determined in advance.

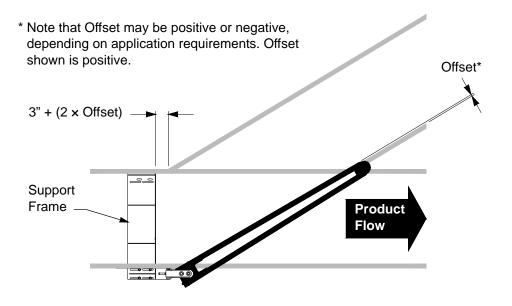


Figure G - 4 — Determining the Installation Location — Opposite Side Installation

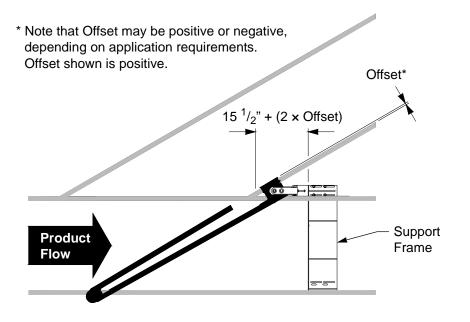


Figure G - 5 — Determining the Installation Location — Junction Side Installation

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### Install the Support Assembly

Place the support assembly on a platform scissor-jack with casters. Position the assembly under the mainline conveyor at the installation location. Carefully raise the assembly, with the pivot shaft oriented upright, until the top of the support frame abuts the underside of the conveyor side rails (see Figure G - 6).

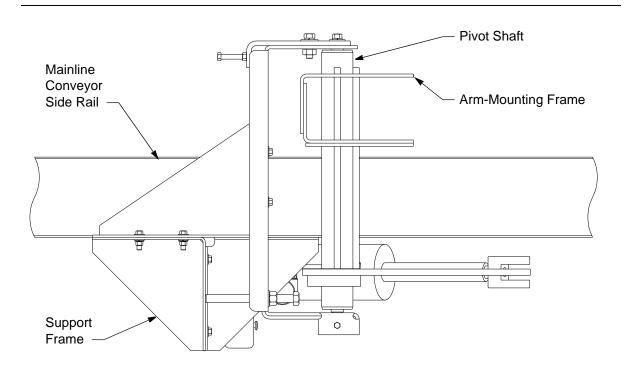


Figure G - 6 - Positioning the Support Frame

Bolt the support frame to the underside of the side rails. Be certain to install the stiffener plate on the top of the lower flange of the rail on the pivot-assembly side (see Figure G - 7). The stiffener plate is essential to providing the necessary structural support for the case deflector.

#### Caution!

The stiffener plate is an essential structural member. Failure to install the stiffener plate properly may result in unstable deflector operation and cause damage to the conveyor side rail.

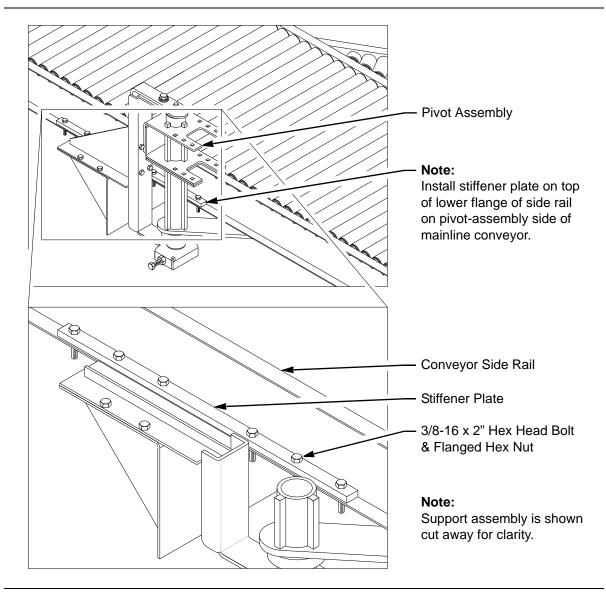


Figure G - 7 - Installing the Stiffener Plate

#### Install the Deflector Arm

Before installing the deflector arm, make certain that the arm faces are oriented properly.

- When plain faces are furnished on both sides, the faces are reversible.
- The faces of UHMW-face and wheel-face arms are not reversible. Make certain that in the "deflect" position, the UHMW face or wheel face is oriented toward the on-coming product.

To provide adequate support for the arm during installation, set a wood block (or similar object) on the conveying surface, and rest the free end of the deflector arm on the block. The height of the block should be equal to the proper clearance between the conveying surface and the underside of the arm. When positioning the deflector arm, note that the flanges of the arm faces fit inside the arm mounting frame. Make certain that all fasteners are tight.

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Remove the support block, and swing the deflector arm manually to make sure that arm movement allows the proper clearance above the conveyor. If clearance deviates from the specified clearance by more than  $\pm 1/16$ " through the full swing of the arm, adjust the pivot assembly as follows (see Figure G - 8):

- Advance-Retard Adjustment Shifts the pivot assembly forward or backward, parallel to the direction of product travel.
- Height Adjustment Raises and lowers the pivot assembly.
- Pitch Adjustment Tilts the vertical axis of the pivot shaft forward or backward parallel to the direction of product travel.
- Roll Adjustment Tilts the vertical axis of the pivot shaft from side to side, perpendicular to the direction of product travel.

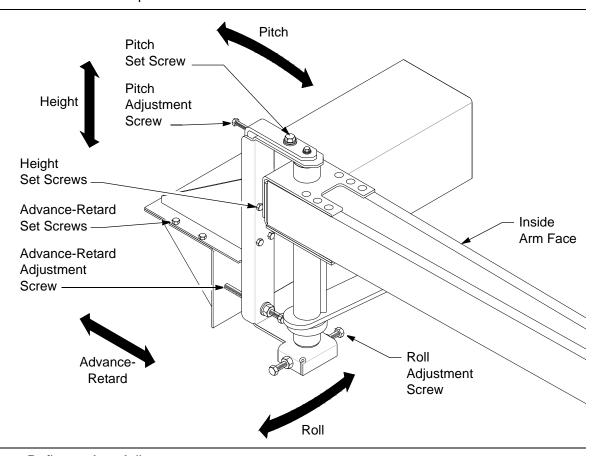


Figure G - 8 — Deflector Arm Adjustments

Make the following connections, installations and adjustments:

- Reconnect the pivot arm to the cylinder-rod clevis (see Figure G 2).
- Replace the air filter bottom cover (see Figure G 9).
- Connect the compressed-air supply to the air filter intake port (see Figure G 9).
- Make electrical and control connections in accordance with the project specifications.

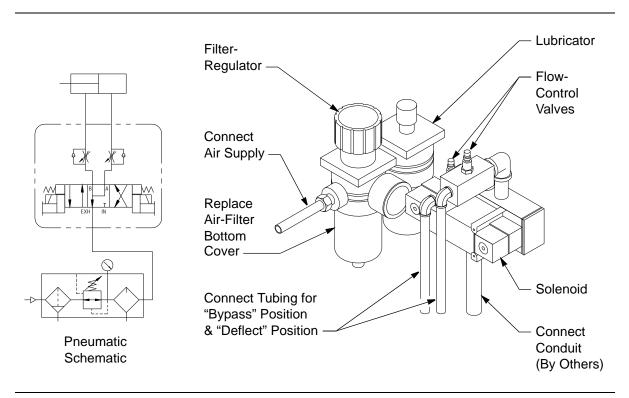


Figure G - 9 — Pneumatic Controls

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# **Check Proximity Switches (Optional)**

On units furnished with proximity switches (for detecting deflector-arm position), check the positioning of the proximity switches, and adjust as necessary (see Figure G - 10). To check the positioning, move the deflector arm to each terminal position ("deflect" and "bypass"), and check to confirm that the corresponding signal is received.

- When the deflector arm is in the "bypass" position, the "bypass" proximity switch should be "On."
- When the deflector arm is in the "deflect" position, the "deflect" proximity switch should be "On."

If no signal is received when a proximity switch should be "On," adjust the position of the proximity switch closer to the rocker.

#### CAUTION:

Make certain to provide some clearance between the proximity switch and the rocker (when the rocker is in the corresponding terminal position). If the rocker contacts the proximity switch during deflector-arm operation, damage to the proximity switch may occur.

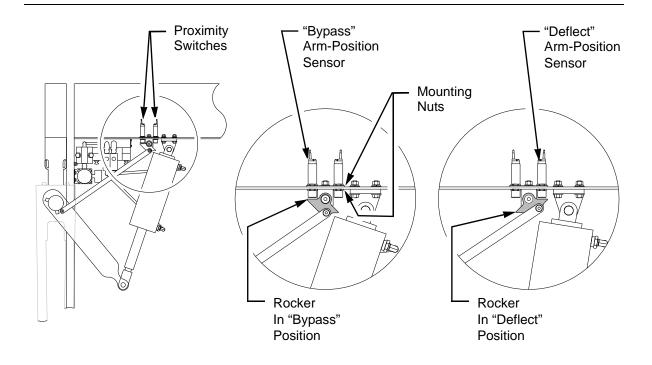


Figure G - 10 — Arm-Position Proximity Switches (Optional)



### Pressure Adjustment & Final Check

- · Make certain that all fasteners are tight.
- Adjust the pressure regulator (initial pressure of 60 psi is recommended).
- Adjust the two flow-control valves located on top of the solenoid and leading to the ports
  of the pneumatic cylinder (one for the "deflect" position, and one for the "bypass" position). Make certain that the valves are adjusted for maximum flow.
- Test-operate the case deflector by activating the solenoid manually. Observe the speed of operation and the amount of shaking of the arm and of the mainline conveyor at the end of both arm movements.
- Adjust the pressure regulator and the two flow-control valves as necessary to achieve the
  desired cycle speed. Make certain that the cycle speed does not shake the case-deflector
  assembly or mainline conveyor excessively.
- Make certain that all fasteners are tight.
- Repeat the test operation and recheck as necessary to ensure that the installation is secure.

When secure installation and proper operation are verified, place the unit in service.

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#### SECTION H:MAINTENANCE

#### CAUTION:

Before performing maintenance on a conveyor, make certain that the power disconnect is locked in the "Open" position and tagged to prevent accidental or unexpected application of power.

Do not perform maintenance while the conveyor is running unless specifically instructed to do so in this manual.

Maintenance must be performed only by qualified personnel who are trained in normal and emergency operations of the conveyor and who are knowledgeable of all safety devices, their locations, and their functions.

#### Before restarting a conveyor:

- Remove all foreign objects from the conveyor.
- Be sure that all guards and safety devices are properly installed and working.
- Make sure that all persons are clear of the conveyor and are aware that the conveyor is about to be restarted.

## Initial Start-Up & Run-In Period

Before starting up the conveyor initially, perform the following checks, and take corrective action as necessary:

- Check the general structure and all safety guards and devices to ensure that the unit has been installed properly, and make certain that all fasteners are tightened securely.
- Make certain that the fasteners securing the deflector arm faces to the mounting frame are tight.
- Check that the set screws in the pivot assembly are properly adjusted and tight.
- Check the settings of the pressure regulator and of the flow-control valves.

During the start-up and run-in period, spend ample time watching the conveyor system, and especially listening to it. Become familiar with the sounds of ordinary operation. Most problems that occur make distinctive sounds – thumps, rattles, and squeaks – but these distinctive sounds can be recognized only in contrast to the sound of normal operation as a baseline. The importance of listening to the sound of normal operation cannot be underestimated.

For the first week of operation, check the listed items daily and take corrective action as necessary. For the following three weeks, check the items listed weekly. After the first four weeks, follow the recommended schedule.

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## **Scheduled Maintenance**

During the first 40 hours of operation, all newly installed equipment should be inspected frequently and serviced as needed. Thereafter, an appropriate maintenance program should be established and followed.

A recommended schedule for preventive maintenance is presented herein (see Table H - 1). The recommended schedule is predicated on typical operation for 8 hours per day, 40 hours per week, above freezing temperature (40°F to 110°F). Continuous-duty operation or operation under extreme environmental conditions may require more frequent maintenance. Operators and maintenance personnel should continually monitor the equipment under actual operating conditions and make adjustments to the recommended schedule accordingly.

Maintaining separate service log sheets on each type of conveyor is recommended for plants operating more than one shift. Each log sheet should show the dates, detailed inspection and service information, and the names or initials of persons performing the inspection or service.

Table H - 1 — Scheduled Maintenance Summary

Interval	Maintenance	Lubrication	Oil Level	Tension	Wear	Alignment	Fasteners	Set Screws	Proper	Physical	Operation
	General Inspection						Χ	Х	Χ	Χ	Χ
Daily (8 Hours)	Structure				Χ		Χ			Χ	
	Electrical Devices										Χ
Weekly	Control Devices						Χ			Χ	Χ
(40 Hours)	Safety Guards and Devices						Χ			Χ	
	Air Pressure										
Monthly	Arm Movement										Х
(175 Hours)	Arm Clearance					Х					
	Pivot Assembly				Χ	Χ		Х	Х	Χ	Х
	Air Filter									Χ	
Quarterly (525 Hours)	Air Lubricator		Χ							Χ	
	Support Assembly						Χ			Χ	

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#### **Daily Maintenance**

## Every 8 hours of operation

At the beginning of every shift, conduct a general walk-through inspection of the entire conveyor system while it is running. Walk slowly and listen attentively for unusual noises. Keep a sharp eye for unusual movement of any conveyor component. If any irregularity is detected, inspect the conveyor closely to identify the cause.

- If product has spilled or fallen out of its packaging and become lodged in the conveyor, stop the conveyor and remove the product. Liquids collecting on a conveyor can cause slippage.
- If a conveyor component has been damaged, determine whether the damage presents an unsafe condition. If an unsafe condition does exist, interrupt conveyor operation immediately, and correct the problem before resuming operation. If an unsafe condition does not exist, make a note of the damage, and schedule repairs in accordance with company maintenance policy. It may be useful to mark the location of the problem in order to find it again at the time for repair.
- If any problem is the result of failure to follow established procedures, make certain that the persons responsible understand and follow the proper procedures. If the established procedures have been followed, discuss the problem with the appropriate supervisor to determine whether procedures should be revised.

Examine the structure to detect damaged or wearing components, and to ensure that the structure is sound and that fasteners are tight. Check the physical condition of the conveyor for loose fasteners, damaged or wearing components, buildup of dust and product spillage. Note that carton dust entering bearings can cause them to deteriorate and shorten the service life of rollers.

Inspect electrical devices, such as proximity sensors, etc. Make certain that they are positioned and aligned properly. Clean lenses and reflectors of optical devices daily. For additional maintenance measures, refer to the technical literature provided by the manufacturer of the device.

## Weekly Maintenance

# Every 40 hours of operation

Check all control devices for physical condition and proper operation, and make certain that all fasteners are tight.

Make certain that all guards and safety devices are intact and that all fasteners are tight. Check for signs of oil leakage on the floor. If leakage persists or the amount of leakage is significant, repair or replace the leaking device.

# **Monthly Maintenance**

# Every 160 hours of operation

Check the deflector arm for proper operation. Check the clearance between the deflector arm and the conveying surface. Check the pivot assembly for physical condition and for proper adjustment. Make certain that the pivot assembly set screws are tight. Check the air pressure.

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### **Quarterly Maintenance**

Every 520 hours of operation

Filter-Regulator – Check the physical condition of the air filter. If the filter element is laden with sediment, clean the filter as follows:

- Depressurize the system.
- Unscrew the polycarbonate bowl.
- Unscrew the filter element from the filter head.
- Wash the filter element with a cleaning solvent.
- Dry the filter element thoroughly.
- Reinstall the filter element to the filter head.
- Replace the polycarbonate bowl.
- Repressurize the system.

**CAUTION:** To avoid closing internal ports, be careful not to screw fittings too far into the body of the filter unit. Normally finger-tight plus one turn will seal.

Lubricator - Check the oil level in the air lubricator and replenish as necessary. Oil may be added to the lubricator while the system is under pressure. Replenish oil as follows:

- Remove the filler plug (located on top of the lubricator body) slowly to relieve pressure in the bowl.
- Insert a long spout or funnel into the filler hole.
- · Add oil.
- Remove the spout or funnel.
- Replace the filler plug.

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# **Troubleshooting**

The troubleshooting information provided herein pertains specifically to the case deflector. For additional troubleshooting information, refer to the "Maintenance" section of the manual for the conveyor on which this equipment is installed.

**CAUTION:** Do not clear jams or reach into any unit unless the electrical power for the mainline and junction conveyors is turned "Off." Make certain that all moving parts have stopped moving completely. To avoid personal injury and equipment damage, lock out and tag out the conveyor controls before attempting to correct any malfunction.

Table H - 2 - Basic Troubleshooting

Problem	Cause	Solution		
Carton collides with moving deflector arm	Arm movement is too slow.	Determine whether arm move- ment is too slow in one direc- tion or in both directions.		
		<ul> <li>If arm movement is too slow in one direction, adjust the corresponding flow-control valve to increase flow rate.</li> </ul>		
		<ul> <li>If arm movement is too slow in two directions, adjust the pressure regula- tor to increase pressure.</li> </ul>		
	Product spacing is too tight.	Take corrective action to increase product spacing.		
Arm movement is too slow in one direction	Flow-control valve setting is too low.	Adjust flow-control valve to increase flow rate.		
Arm movement is too slow in both directions	Pressure regulator setting is too low.	Adjust pressure regulator to increase pressure.		
	Both flow-control valve settings are too low.	Adjust both flow-control valves to increase flow rate.		
Arm movement is too fast in one direction	Flow-control valve setting is too high.	Adjust flow-control valve to decrease flow rate.		
Arm movement is too fast in both directions	Pressure regulator setting is too high.	Adjust pressure regulator to decrease pressure.		
	Both flow-control valve settings are too high.	Adjust both flow-control valves to decrease flow rate.		

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Problem	Cause	Solution
Carton or product damage results from contact with deflector arm	Arm movement is too fast.	Determine whether arm move- ment is too fast in one direc- tion or in both directions, and adjust the flow-control valves accordingly.
	Deflector arm is still moving when product arrives.	Adjust timing of arm action in relation to product movement. Adjust product spacing as necessary.
	Arm touches carrying surface.	Adjust arm clearance to within design limits.
		Reconfigure product as necessary to avoid damage with existing clearance.
	Friction between product and conveying surface is too large.	Reconfigure product, or main- line conveyor, or both, as nec- essary to reduce coefficient of friction.

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# SECTION I: SPARE PARTS

# Parts Replacement

Certain parts are classified as "spare parts" because they are necessary for the component to function and prone to failure. The manufacturer recommends stocking a supply of these spare parts in order to minimize down time when failure occurs. The illustrations that follow show these parts, their locations, and related parts which may not be classified as spare parts. Callouts in the illustrations are keyed to tables which follow the illustrations. The tables list part numbers and descriptions and indicate whether each part is classified as a spare part. Instructions for installing parts is provided in Section G, *Installation Procedures*.

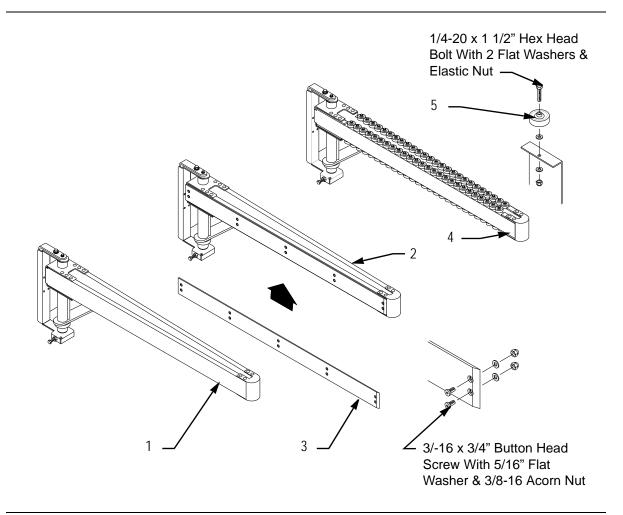


Figure I - 1 — Case Deflector Arm Parts

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Table I - 2 —Case Deflector Arm Face Component Part Numbers (see Figure I - 1)

Kov	Part Description -	Mainline Conveyor Width (Inches)							
Key		16	22	28	34	40			
1	Arm Rail, Plain Face	737843	737844	737845	737846	737847			
2	Arm Rail, UHMW Face	737848	737849	737850	737851	737852			
3	UHMW Plate	737853	737854	737855	737856	737857			
4	Arm Rail, Wheel Face	737858	737859	737860	737861	737862			
5	Skate Wheel, 1 15/16" O. D., 1/4" I. D.	1000422	1000422	1000422	1000422	1000422			

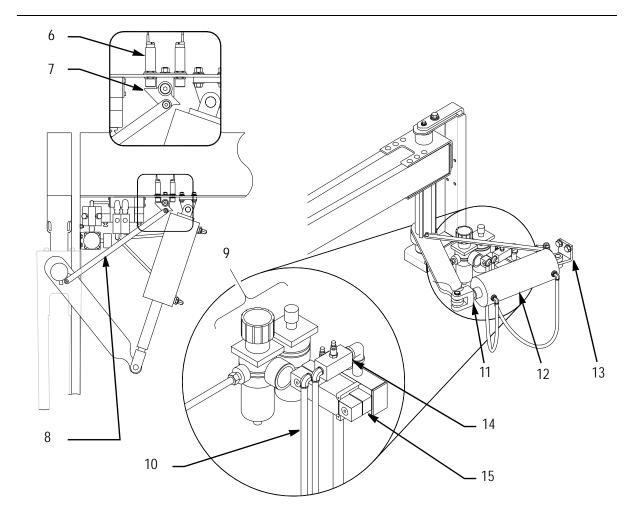


Figure I - 3 — Control Components

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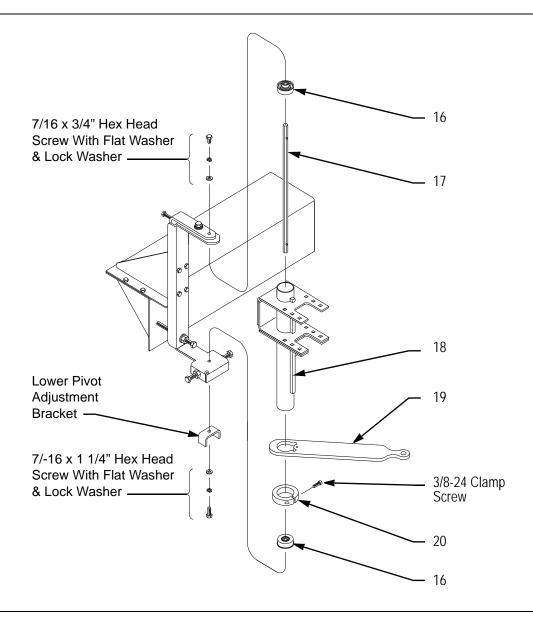


Figure I - 4 — Pivot Assembly Components

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Table I - 5 - Control & Pivot Assembly Components

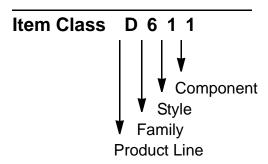
Key	Part Description	Part Number	Spare Part
6	Sensor, Proximity 18mm DC	270271	Yes
7	Case Deflector Rocker (Proximity Switch Target)	737886	Yes
8	Case Deflector Rocker Arm	737885	Yes
9	Filter, Regulator, Lubricator & Gage Assembly	271736	Yes
10	3/8" Nylon Tube, Alkon # NY66-N (Specify length in feet)	271570	Yes
11	Bimba Cylinder Clevis & Pin, ARC2	737903	Yes
12	Bimba Cylinder, DWC-1258-2	737901	Yes
13	Bimba CylinderMounting Kit, MC-125	737902	Yes
14	Flow Control Valve	270975	Yes
15	Solenoid Valve, Case Deflector		Yes
	Mac 24 Volt	270978	
	Mac 120 Volt	742265	
16	Bearing, Miller MF-2511-HSP	350372	Yes
17	Case Deflector Pivot Roller Axle, P	737906	Yes
18	Case Deflector Pivot Roller Assembly (Includes Items #16 and #17)	737898	No
19	Case Deflector Pivot Bracket, Cylinder Rod End	737888	Yes
20	Shaft Collar, CTC-174, Reid Tool	737904	No

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## SECTION J: PRODUCT INDEX

# **CS Case Deflector**



- (F1) Arm Face
- (F2) Solenoid Valve
- (F3) Proximity Switch
- (F4) Mounting Depth

Description	Drawing Number	Width of Mainline Conveyor (W)					
Description		16"	22"	28"	34"	40"	
DEF CS ASSY RH W	19699 D	825951	825952	825953	825954	825955	
DEF CS ASSY LH W	19643 D	825930	825931	825932	825933	825934	
DEF CS ASSY RH 10" DEEP W	19746 D	825961	825962	825963	825964	825965	
DEF CS ASSY LH 10" DEEP W	19745 D	825956	825957	825958	825959	825960	

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